Name:_____

Section 13.6-14.2 Review

Brief Summary of 13.6-14.2 (see full summaries at the end of each section in the course textbook.)

• Use the figure below to create a table that describes conversion from rectangular (x, y, z) to cylindrical coordinates (r, θ, z) and vice versa.



• Use the figure below to create a table that describes conversion from rectangular (x, y, z) to spherical coordinates (ρ, θ, ϕ) and vice versa.



• Product rules:

Scalar times vector:
$$\frac{d}{dt}(f(t)\mathbf{r}(t)) =$$
_____.

Dot product:
$$\frac{d}{dt}(\mathbf{r_1}(t) \cdot \mathbf{r_2}(t)) =$$
______.

Cross product:
$$\frac{d}{dt}(\mathbf{r_1}(t) \times \mathbf{r_2}(t)) =$$

• If $r'(t_0)$ is nonzero, then it points in the direction ______ to the curve at _____. The tangent line at $r(t_0)$ has vector parametrization ______.

Section 13.6 Additional Exercises

1. Describe the intersection of the horizontal plane z = h and the hyperboloid $-x^2 - 9y^2 + 25z^2 = 1$. For which values of h is the intersection empty?

Section 13.7 Additional Exercises

- 1. Convert $(1, \frac{\pi}{2}, -2)$ from cylindrical to rectangular coordinates.
- 2. Convert $(1, \sqrt{3}, 7)$ from rectangular to cylindrical coordinates.
- 3. Sketch the set $r = \sin \theta$ described in cylindrical coordinates.
- 4. Convert $(3, 0, \frac{\pi}{2})$ from spherical to rectangular coordinates.
- 5. Convert (1, 1, 1) from rectangular to spherical coordinates.
- 6. Convert (2, 0, 2) from cylindrical to spherical coordinates.

Section 14.1-14.2 Additional Exercises

1. The function $\mathbf{r}(t) = \langle \sin t, 0, 4 + \cos t \rangle$ traces a circle. Determine the radius, center, and plane containing the circle.

In Exercises 2-4, find a parametrization of the curve.

2. The vertical line passing through the point (3, 2, 0).

- 3. The circle of radius 2 with center (1, 2, 5) in a plane parallel to the yz-plane.
- 4. The intersection of the surfaces $y^2 z^2 = x 2$, and $y^2 + z^2 = 9$ using t = y as the parameter.

In exercises 5-7, let $\mathbf{r_1}(t) = \langle t^2, t^3, t \rangle$ and $\mathbf{r_2}(t) = \langle e^{3t}, e^{2t}, e^t \rangle$.

5. Find $r'_1(t)$

6. Find $\frac{d}{dt}(\mathbf{r_1}(t) \cdot \mathbf{r_2}(t))$.

7. Find $\frac{d}{dt}(\mathbf{r_1}(t) \times \mathbf{r_2}(t))$.

8. Calculate $\frac{d}{dt}(\mathbf{r} \times \mathbf{r'})$, where $\mathbf{r}(t) = \langle t, t^2, e^t \rangle$.